

HEF4060B

14-stage ripple-carry binary counter/divider and oscillator

Rev. 10 — 8 November 2021

Product data sheet

1. General description

The HEF4060B is a 14-stage ripple-carry counter/divider and oscillator with three oscillator terminals (RS, REXT and CEXT), ten buffered parallel outputs (Q3 to Q9 and Q11 to Q13) and an overriding asynchronous master reset (MR). The oscillator configuration allows design of either RC or crystal oscillator circuits. The oscillator may be replaced by an external clock signal at input RS. In this case, keep the oscillator pins (REXT and CEXT) floating. The counter advances on the HIGH-to-LOW transition of RS. A HIGH level on MR clears all counter stages and forces all outputs LOW, independent of the other input conditions. Inputs include clamp diodes. This enables the use of current limiting resistors to interface inputs to voltages in excess of V_{DD} .

2. Features and benefits

- Wide supply voltage range from 3.0 V to 15.0 V
- CMOS low power dissipation
- High noise immunity
- Complies with JEDEC standard JESD 13-B
- Tolerant of slow clock rise and fall times
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- ESD protection:
 - HBM JESD22-A114F exceeds 2000 V
 - MM JESD22-A115-A exceeds 200 V
- Specified from -40 °C to +85 °C

3. Ordering information

Table 1. Ordering information

| Type number | Package | | | |
|-------------|-------------------|---------|--|----------|
| | Temperature range | Name | Description | Version |
| HEF4060BT | -40 °C to +85 °C | SO16 | plastic small outline package; 16 leads; body width 3.9 mm | SOT109-1 |
| HEF4060BTT | -40 °C to +85 °C | TSSOP16 | plastic thin shrink small outline package; 16 leads; body width 4.4 mm | SOT403-1 |

4. Functional diagram

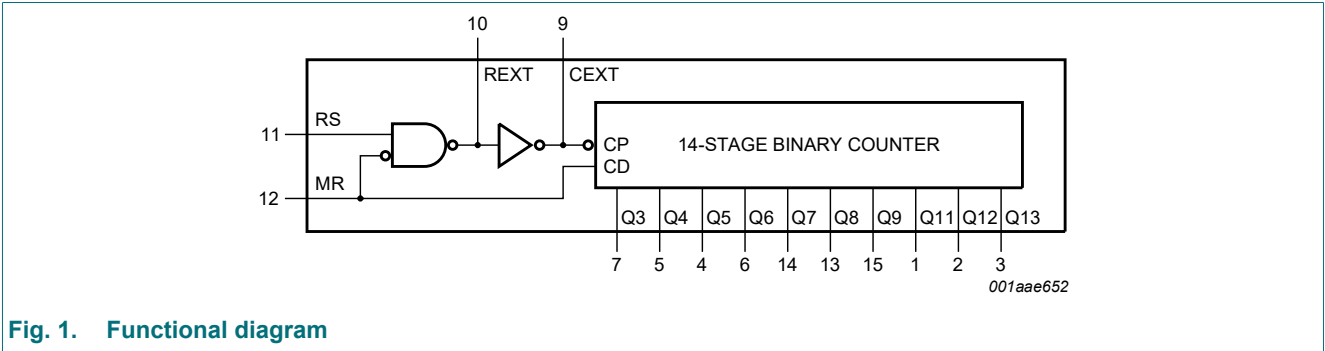


Fig. 1. Functional diagram

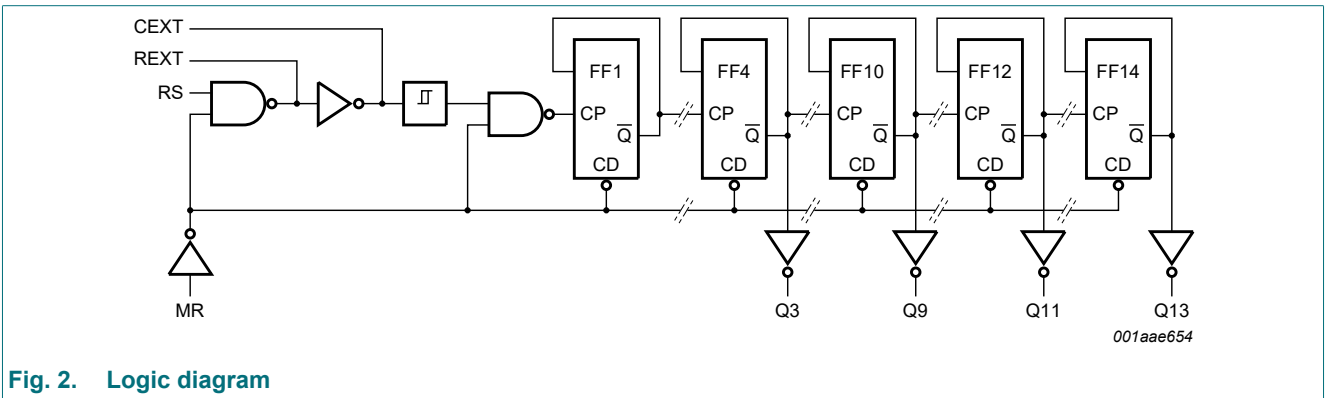


Fig. 2. Logic diagram

5. Pinning information

5.1. Pinning

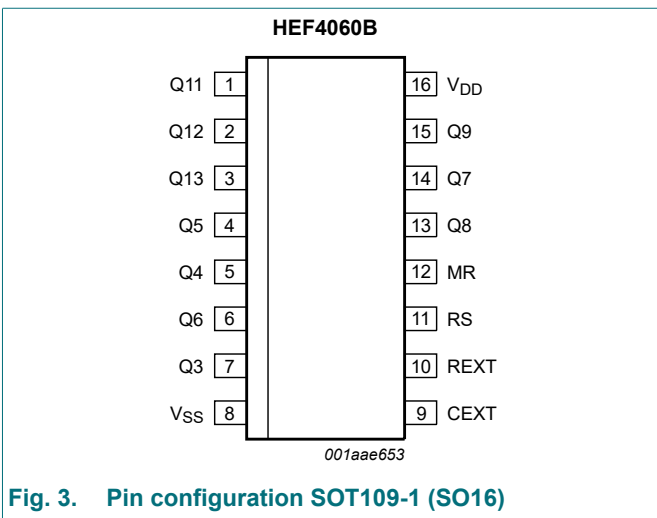


Fig. 3. Pin configuration SOT109-1 (SO16)

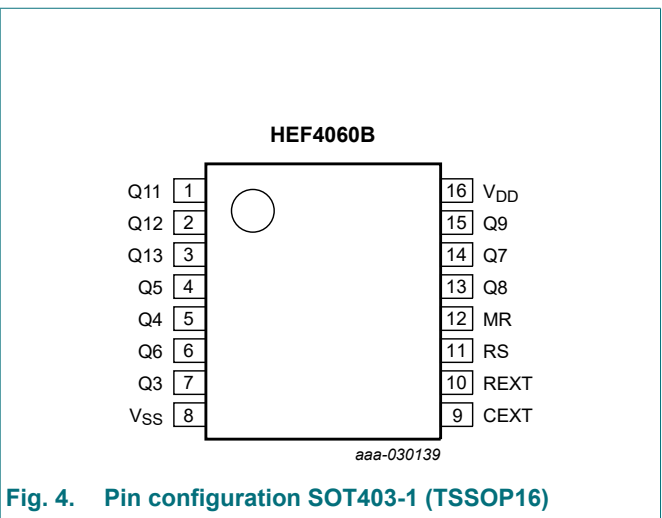


Fig. 4. Pin configuration SOT403-1 (TSSOP16)

5.2. Pin description

Table 2. Pin description

| Symbol | Pin | Description |
|-----------------|------------------------|-------------------------------|
| Q11 to Q13 | 1, 2, 3 | counter output |
| Q3 to Q9 | 7, 5, 4, 6, 14, 13, 15 | counter output |
| V _{SS} | 8 | ground supply voltage |
| CEXT | 9 | external capacitor connection |
| REXT | 10 | oscillator pin |
| RS | 11 | clock input/oscillator pin |
| MR | 12 | master reset |
| V _{DD} | 16 | supply voltage |

6. Functional description

Table 3. Function table

H = HIGH voltage level; L = LOW voltage level; ↑ = LOW-to-HIGH clock transition; ↓ = HIGH-to-LOW clock transition.

| Input | | Output |
|-------|----|-------------------------|
| RS | MR | Q3 to Q9 and Q11 to Q13 |
| ↑ | L | no change |
| ↓ | L | count |
| X | H | L |

7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|------------------|-------------------------|---|------|-----------------------|------|
| V _{DD} | supply voltage | | -0.5 | +18 | V |
| I _{IK} | input clamping current | V _I < -0.5 V or V _I > V _{DD} + 0.5 V | - | ±10 | mA |
| V _I | input voltage | | -0.5 | V _{DD} + 0.5 | V |
| I _{OK} | output clamping current | V _O < -0.5 V or V _O > V _{DD} + 0.5 V | - | ±10 | mA |
| I _{I/O} | input/output current | | - | ±10 | mA |
| I _{DD} | supply current | | - | 50 | mA |
| T _{stg} | storage temperature | | -65 | +150 | °C |
| T _{amb} | ambient temperature | | -40 | +85 | °C |
| P _{tot} | total power dissipation | T _{amb} -40 °C to +85 °C | - | 500 | mW |
| P | power dissipation | per output | - | 100 | mW |

8. Recommended operating conditions

Table 5. Recommended operating conditions

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---------------------|-------------------------------------|------------------------|-----|-----|----------|-----------------|
| V_{DD} | supply voltage | | 3 | - | 15 | V |
| V_I | input voltage | | 0 | - | V_{DD} | V |
| T_{amb} | ambient temperature | in free air | -40 | - | +85 | °C |
| $\Delta t/\Delta V$ | input transition rise and fall rate | input MR | | | | |
| | | $V_{DD} = 5\text{ V}$ | - | - | 3.75 | $\mu\text{s/V}$ |
| | | $V_{DD} = 10\text{ V}$ | - | - | 0.5 | $\mu\text{s/V}$ |
| | | $V_{DD} = 15\text{ V}$ | - | - | 0.08 | $\mu\text{s/V}$ |

9. Static characteristics

Table 6. Static characteristics

$V_{SS} = 0\text{ V}$; $V_I = V_{SS}$ or V_{DD} unless otherwise specified.

| Symbol | Parameter | Conditions | V_{DD} | $T_{amb} = -40\text{ °C}$ | | $T_{amb} = 25\text{ °C}$ | | $T_{amb} = 85\text{ °C}$ | | Unit |
|----------|---------------------------|--------------------------|----------|---------------------------|-----------|--------------------------|-----------|--------------------------|-----------|---------------|
| | | | | Min | Max | Min | Max | Min | Max | |
| V_{IH} | HIGH-level input voltage | $ I_O < 1\ \mu\text{A}$ | 5 V | 3.5 | - | 3.5 | - | 3.5 | - | V |
| | | | 10 V | 7.0 | - | 7.0 | - | 7.0 | - | V |
| | | | 15 V | 11.0 | - | 11.0 | - | 11.0 | - | V |
| V_{IL} | LOW-level input voltage | $ I_O < 1\ \mu\text{A}$ | 5 V | - | 1.5 | - | 1.5 | - | 1.5 | V |
| | | | 10 V | - | 3.0 | - | 3.0 | - | 3.0 | V |
| | | | 15 V | - | 4.0 | - | 4.0 | - | 4.0 | V |
| V_{OH} | HIGH-level output voltage | $ I_O < 1\ \mu\text{A}$ | 5 V | 4.95 | - | 4.95 | - | 4.95 | - | V |
| | | | 10 V | 9.95 | - | 9.95 | - | 9.95 | - | V |
| | | | 15 V | 14.95 | - | 14.95 | - | 14.95 | - | V |
| V_{OL} | LOW-level output voltage | $ I_O < 1\ \mu\text{A}$ | 5 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| | | | 10 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| | | | 15 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| I_{OH} | HIGH-level output current | $V_O = 2.5\text{ V}$ | 5 V | - | -1.7 | - | -1.4 | - | -1.1 | mA |
| | | $V_O = 4.6\text{ V}$ | 5 V | - | -0.52 | - | -0.44 | - | -0.36 | mA |
| | | $V_O = 9.5\text{ V}$ | 10 V | - | -1.3 | - | -1.1 | - | -0.9 | mA |
| | | $V_O = 13.5\text{ V}$ | 15 V | - | -3.6 | - | -3.0 | - | -2.4 | mA |
| I_{OL} | LOW-level output current | $V_O = 0.4\text{ V}$ | 5 V | 0.52 | - | 0.44 | - | 0.36 | - | mA |
| | | $V_O = 0.5\text{ V}$ | 10 V | 1.3 | - | 1.1 | - | 0.9 | - | mA |
| | | $V_O = 1.5\text{ V}$ | 15 V | 3.6 | - | 3.0 | - | 2.4 | - | mA |
| I_I | input leakage current | | 15 V | - | ± 0.3 | - | ± 0.3 | - | ± 1.0 | μA |
| I_{DD} | supply current | $I_O = 0\text{ A}$ | 5 V | - | 20 | - | 20 | - | 150 | μA |
| | | | 10 V | - | 40 | - | 40 | - | 300 | μA |
| | | | 15 V | - | 80 | - | 80 | - | 600 | μA |
| C_I | input capacitance | | - | - | - | - | 7.5 | - | - | pF |

10. Dynamic characteristics

Table 7. Dynamic characteristics

$T_{amb} = 25\text{ }^{\circ}\text{C}$; $V_{SS} = 0\text{ V}$; $C_L = 50\text{ pF}$; $t_r = t_f \leq 20\text{ ns}$; unless otherwise specified.

| Symbol | Parameter | Conditions | V _{DD} | Extrapolation formula[1] | Min | Typ | Max | Unit |
|------------------|-------------------|--|-----------------|--------------------------------------|-----|-----|-----|------|
| t _{pd} | propagation delay | RS → Q3; see Fig. 5 | 5 V [2] | 183 ns + (0.55 ns/pF) C _L | - | 210 | 420 | ns |
| | | | 10 V | 69 ns + (0.23 ns/pF) C _L | - | 80 | 160 | ns |
| | | | 15 V | 42 ns + (0.16 ns/pF) C _L | - | 50 | 100 | ns |
| | | Q _n → Q _n + 1; see Fig. 5 | 5 V | - | - | 25 | 50 | ns |
| | | | 10 V | - | - | 10 | 20 | ns |
| | | | 15 V | - | - | 6 | 12 | ns |
| | | MR → Q _n ; HIGH to LOW see Fig. 5 | 5 V | 73 ns + (0.55 ns/pF) C _L | - | 100 | 200 | ns |
| | | | 10 V | 29 ns + (0.23 ns/pF) C _L | - | 40 | 80 | ns |
| | | | 15 V | 22 ns + (0.16 ns/pF) C _L | - | 30 | 60 | ns |
| t _t | transition time | see Fig. 5 | 5 V [3] | 10 ns + (1.00 ns/pF) C _L | - | 60 | 120 | ns |
| | | | 10 V | 9 ns + (0.42 ns/pF) C _L | - | 30 | 60 | ns |
| | | | 15 V | 6 ns + (0.28 ns/pF) C _L | - | 20 | 40 | ns |
| t _w | pulse width | minimum width; RS HIGH; see Fig. 5 | 5 V | | 120 | 60 | - | ns |
| | | | 10 V | | 50 | 25 | - | ns |
| | | | 15 V | | 30 | 15 | - | ns |
| | | minimum width; MR HIGH; see Fig. 5 | 5 V | | 50 | 25 | - | ns |
| | | | 10 V | | 30 | 15 | - | ns |
| | | | 15 V | | 20 | 10 | - | ns |
| t _{rec} | recovery time | input MR; see Fig. 5 | 5 V | | 160 | 80 | - | ns |
| | | | 10 V | | 80 | 40 | - | ns |
| | | | 15 V | | 60 | 30 | - | ns |
| f _{max} | maximum frequency | input RS; see Fig. 5 | 5 V | | 4 | 8 | - | MHz |
| | | | 10 V | | 10 | 20 | - | MHz |
| | | | 15 V | | 15 | 30 | - | MHz |

[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C_L in pF).

[2] t_{pd} is the same as t_{PHL} and t_{PLH}.

[3] t_t is the same as t_{THL} and t_{TLH}.

Table 8. Power dissipation

Dynamic power dissipation P_D and total power dissipation P_{tot} can be calculated from the formulas shown. $T_{amb} = 25\text{ }^\circ\text{C}$.

| Symbol | Parameter | Conditions | V_{DD} | Typical formula for P_D and P_{tot} (μW)[1] |
|-----------|---------------------------|-----------------------------------|----------|--|
| P_D | dynamic power dissipation | per device | 5 V | $P_D = 700 \times f_i + \sum(f_o \times C_L) \times V_{DD}^2$ |
| | | | 10 V | $P_D = 3300 \times f_i + \sum(f_o \times C_L) \times V_{DD}^2$ |
| | | | 15 V | $P_D = 8900 \times f_i + \sum(f_o \times C_L) \times V_{DD}^2$ |
| P_{tot} | total power dissipation | when using the on-chip oscillator | 5 V | $P_{tot} = 700 \times f_{osc} + \sum(f_o \times C_L) \times V_{DD}^2 + 2 \times C_t \times V_{DD}^2 \times f_{osc} + 690 \times V_{DD}$ |
| | | | 10 V | $P_{tot} = 3300 \times f_{osc} + \sum(f_o \times C_L) \times V_{DD}^2 + 2 \times C_t \times V_{DD}^2 \times f_{osc} + 6900 \times V_{DD}$ |
| | | | 15 V | $P_{tot} = 8900 \times f_{osc} + \sum(f_o \times C_L) \times V_{DD}^2 + 2 \times C_t \times V_{DD}^2 \times f_{osc} + 22000 \times V_{DD}$ |

[1] Where:

- f_i = input frequency in MHz; f_o = output frequency in MHz;
- C_L = output load capacitance in pF;
- V_{DD} = supply voltage in V;
- $\sum(f_o \times C_L)$ = sum of the outputs;
- C_t = timing capacitance (pF);
- f_{osc} = oscillator frequency (MHz).

10.1. Waveforms and test circuit

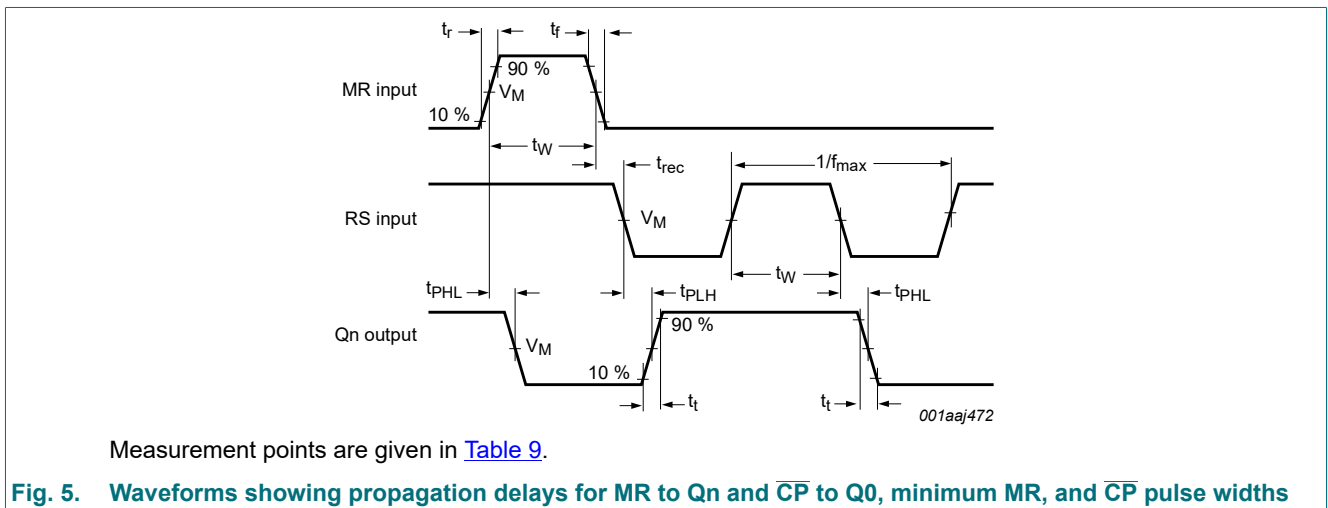
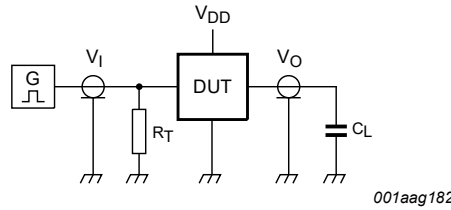


Fig. 5. Waveforms showing propagation delays for MR to Qn and \overline{CP} to Q0, minimum MR, and \overline{CP} pulse widths

Table 9. Measurement points

| Supply voltage | Input | Output |
|----------------|-------------|-------------|
| V_{DD} | V_M | V_M |
| 5 V to 15 V | $0.5V_{DD}$ | $0.5V_{DD}$ |

14-stage ripple-carry binary counter/divider and oscillator



Test data is given in [Table 10](#).

Definitions for test circuit:

DUT = Device Under Test;

C_L = load capacitance including jig and probe capacitance;

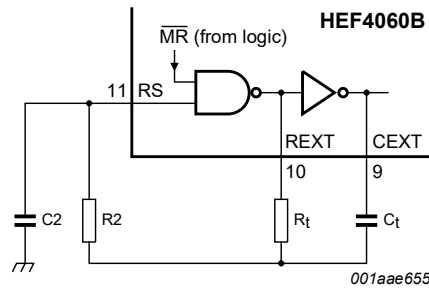
R_T = termination resistance should be equal to the output impedance Z_o of the pulse generator.

Fig. 6. Test circuit for measuring switching times

Table 10. Measurement point and test data

| Supply voltage | Input | | Load |
|----------------|----------------------|--------------|-------|
| V_{DD} | V_I | t_r, t_f | C_L |
| 5 V to 15 V | V_{SS} or V_{DD} | ≤ 20 ns | 50 pF |

11. RC oscillator



Typical formula for oscillator frequency: $f_{osc} = \frac{1}{2.3 \times R_t \times C_t}$

Fig. 7. External component connection for RC oscillator

11.1. Timing component limitations

The oscillator frequency is mainly determined by $R_t \times C_t$, provided $R_t \ll R_2$ and $R_2 \times C_2 \ll R_t \times C_t$. The influence of the forward voltage across the input protection diodes on the frequency is minimized by R_2 . The stray capacitance C_2 should be kept as small as possible. In consideration of accuracy, C_t must be larger than the inherent stray capacitance. R_t must be larger than the LOCMOS (Local Oxidation Complementary Metal-Oxide Semiconductor) 'ON' resistance in series with it, which typically is 500 Ω at $V_{DD} = 5$ V, 300 Ω at $V_{DD} = 10$ V and 200 Ω at $V_{DD} = 15$ V.

The recommended values for these components to maintain agreement with the typical oscillation formula are:

- $C_t \geq 100$ pF, up to any practical value,
- 10 k $\Omega \leq R_t \leq 1$ M Ω .

11.2. Typical crystal oscillator circuit

In Fig. 8, R2 is the power limiting resistor. For starting and maintaining oscillation a minimum transconductance is necessary.

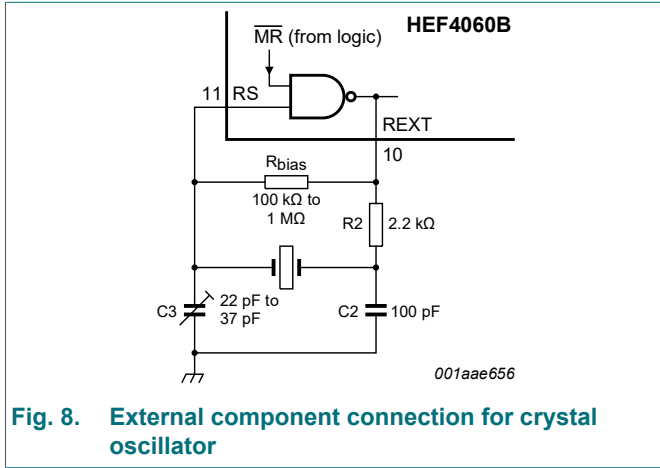


Fig. 8. External component connection for crystal oscillator

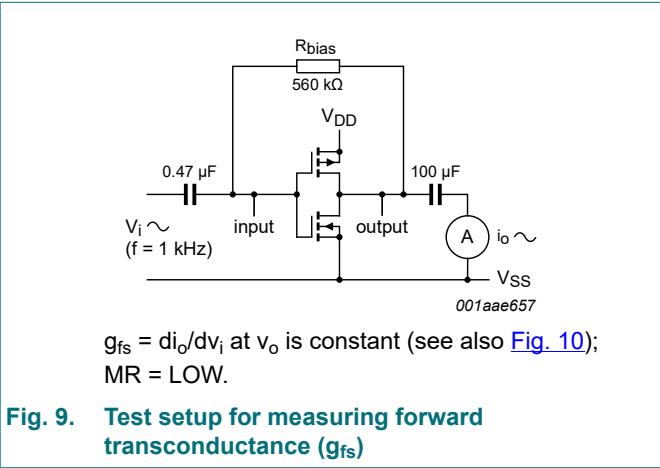


Fig. 9. Test setup for measuring forward transconductance (g_{fs})

$g_{fs} = di_o/dv_i$ at v_o is constant (see also Fig. 10);
MR = LOW.

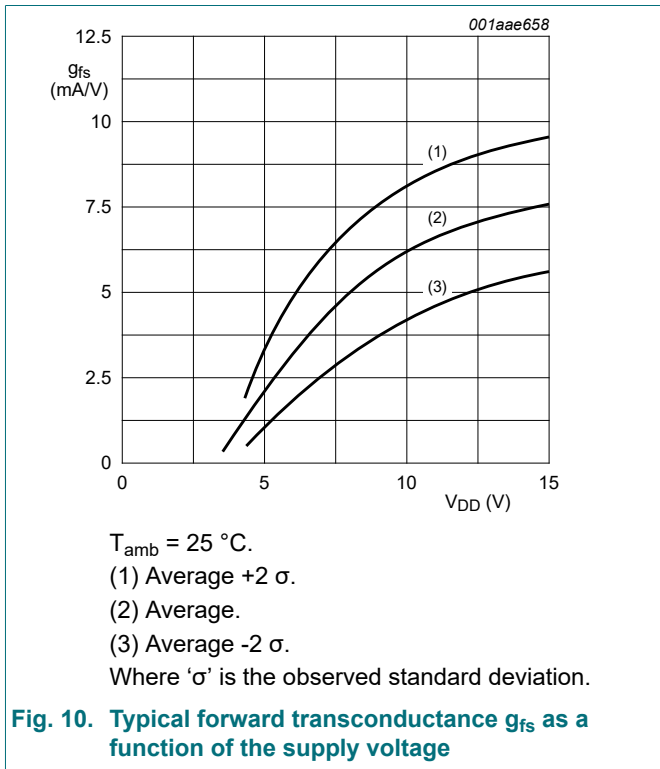


Fig. 10. Typical forward transconductance g_{fs} as a function of the supply voltage

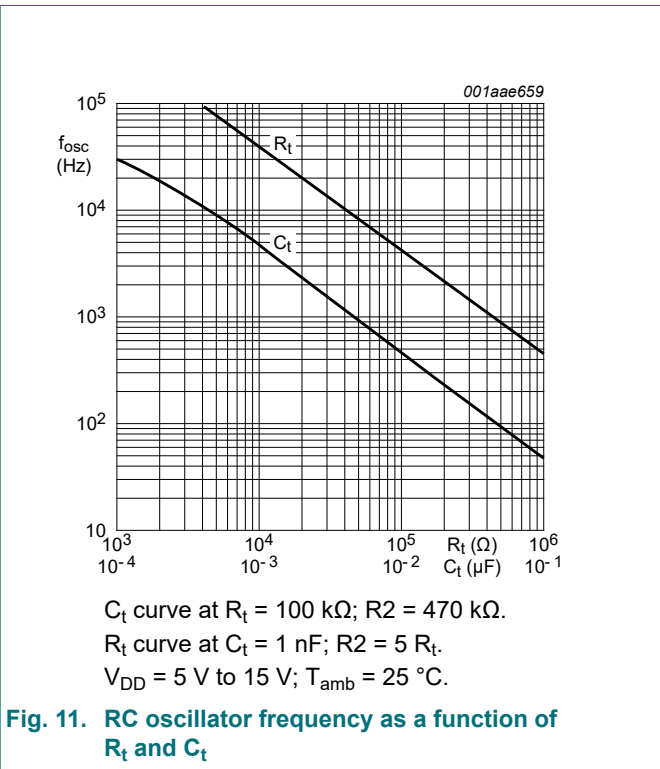
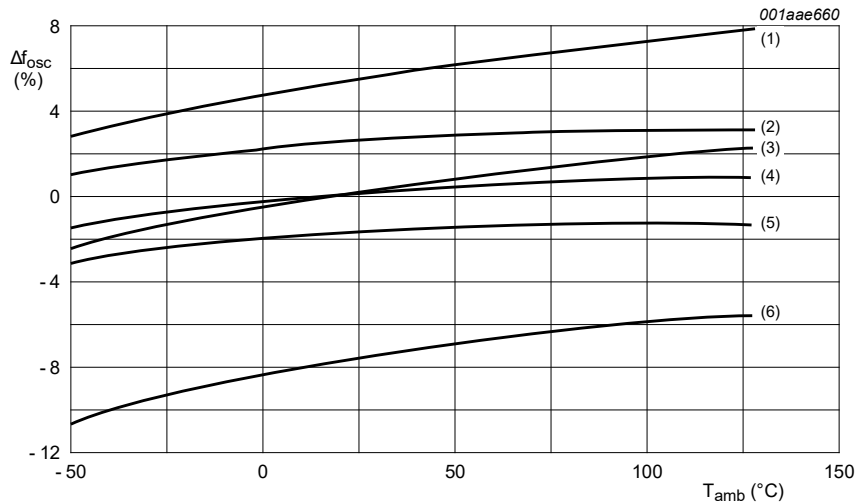


Fig. 11. RC oscillator frequency as a function of R_t and C_t

14-stage ripple-carry binary counter/divider and oscillator



Lines (1) and (2): $V_{DD} = 15$ V.

Lines (3) and (4): $V_{DD} = 10$ V.

Lines (5) and (6): $V_{DD} = 5$ V.

Lines (1), (3), (6): $R_t = 100$ k Ω ; $C_t = 1$ nF; $R_2 = 0$ Ω .

Lines (2), (4), (5): $R_t = 100$ k Ω ; $C_t = 1$ nF; $R_2 = 300$ k Ω .

Referenced at: f_{osc} at $T_{amb} = 25$ °C and $V_{DD} = 10$ V.

Fig. 12. Oscillator frequency deviation (Δf_{osc}) as a function of ambient temperature

12. Package outline

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1



Fig. 13. Package outline SOT109-1 (SO16)

TSSOP16: plastic thin shrink small outline package; 16 leads; body width 4.4 mm

SOT403-1

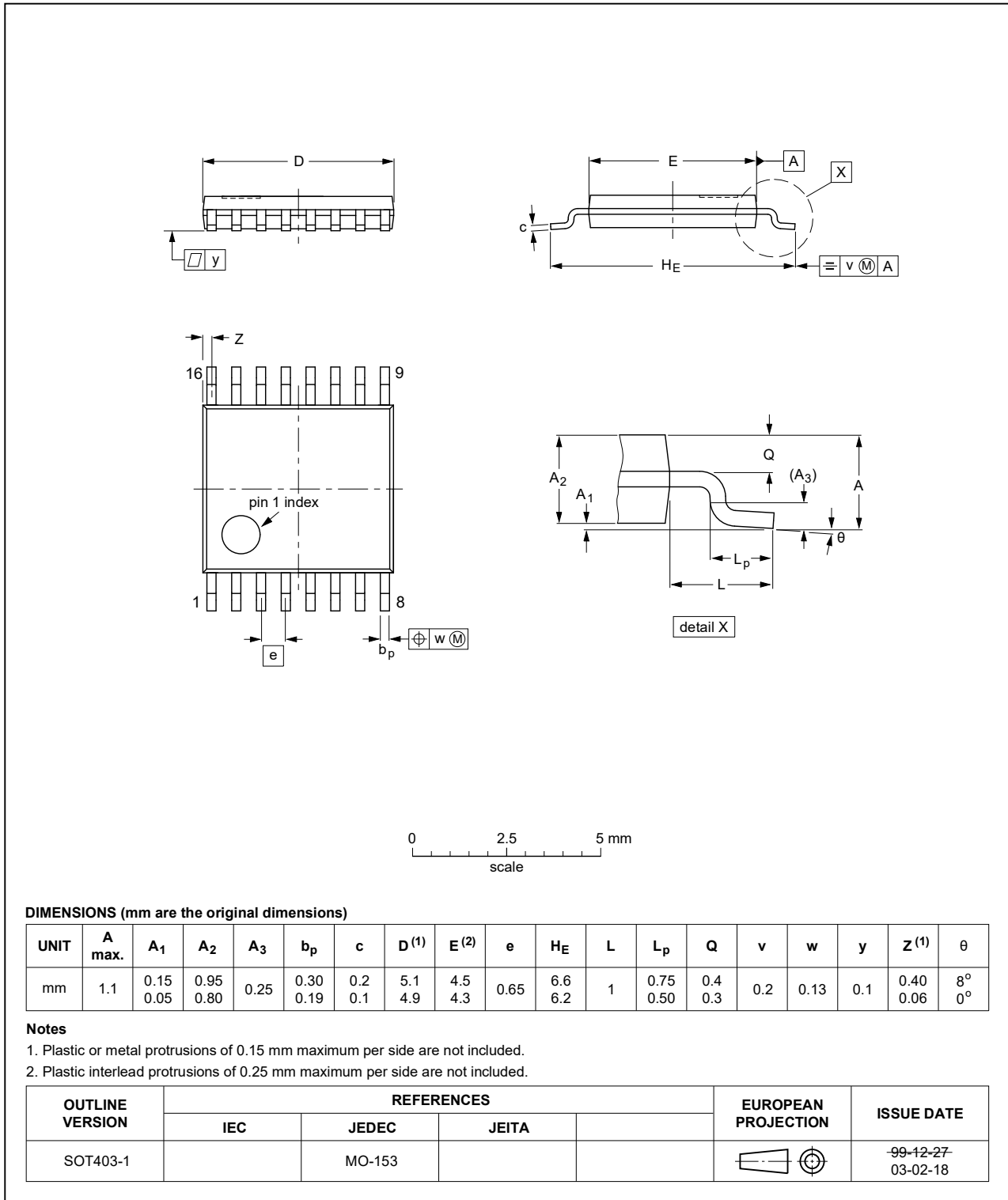


Fig. 14. Package outline SOT403-1 (TSSOP16)

13. Abbreviations

Table 11. Abbreviations

| Acronym | Description |
|---------|-------------------------|
| DUT | Device Under Test |
| ESD | ElectroStatic Discharge |
| HBM | Human Body Model |
| MM | Machine Model |

14. Revision history

Table 12. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|------------------|---|-----------------------|---------------|------------------|
| HEF4060B v.10 | 20211108 | Product data sheet | - | HEF4060B v.9 |
| Modifications: | <ul style="list-style-type: none"> The format of this data sheet has been redesigned to comply with the identity guidelines of Nexperia. Legal texts have been adapted to the new company name where appropriate. Section 1 and Section 2 updated. | | | |
| HEF4060B v.9 | 20190708 | Product data sheet | - | HEF4060B v.8 |
| Modifications: | <ul style="list-style-type: none"> Type number HEF4060BTT (SOT403-1/TSSOP16) added. | | | |
| HEF4060B v.8 | 20160325 | Product data sheet | - | HEF4060B v.7 |
| Modifications: | <ul style="list-style-type: none"> Type number HEF4060BP (SOT38-4) removed. | | | |
| HEF4060B v.7 | 20111116 | Product data sheet | - | HEF4060B v.6 |
| Modifications: | <ul style="list-style-type: none"> Legal pages updated. Changes in "General description" and "Features and benefits". Section "Applications" removed. | | | |
| HEF4060B v.6 | 20110511 | Product data sheet | - | HEF4060B v.5 |
| HEF4060B v.5 | 20091127 | Product data sheet | - | HEF4060B v.4 |
| HEF4060B v.4 | 20090817 | Product data sheet | - | HEF4060B_CNV v.3 |
| HEF4060B_CNV v.3 | 19950101 | Product specification | - | HEF4060B_CNV v.2 |
| HEF4060B_CNV v.2 | 19950101 | Product specification | - | - |

15. Legal information

Data sheet status

| Document status [1][2] | Product status [3] | Definition |
|--------------------------------|--------------------|---|
| Objective [short] data sheet | Development | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet | Qualification | This document contains data from the preliminary specification. |
| Product [short] data sheet | Production | This document contains the product specification. |

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